



Bundesamt für
Kartographie und Geodäsie



hHz monostatic Lunar Laser Ranging at the WLRS

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Introduction

- LLR @ WLRS -



SCOPE

- Good connection to reference frames
- T&F system, good representation of SI second (3 Masers, CS clocks)
- Well defined SLR reference point
 - Station coordinates & velocity (ITRF)
 - Local tie network (system calibration, range bias)
- 10 ps Laser pulse, intrinsic precision < 4 mm RMS
- Good intrinsic system stability, Calibration mean
- Daytime LLR possible

LIMITATION

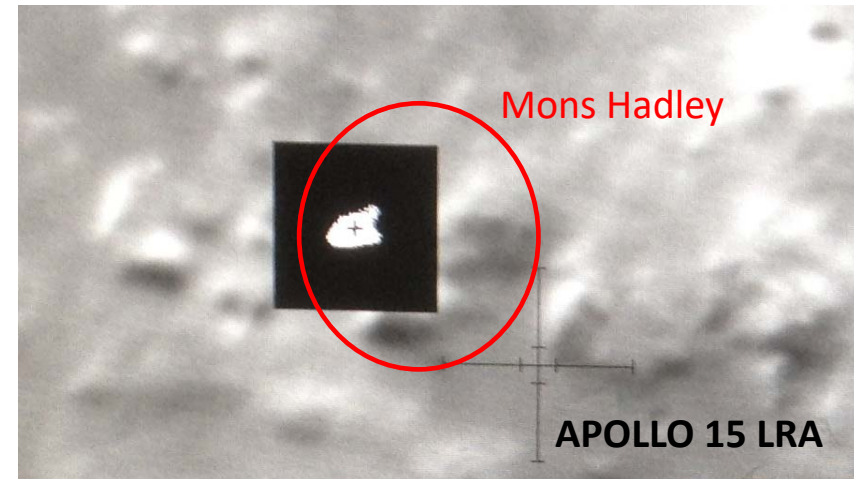
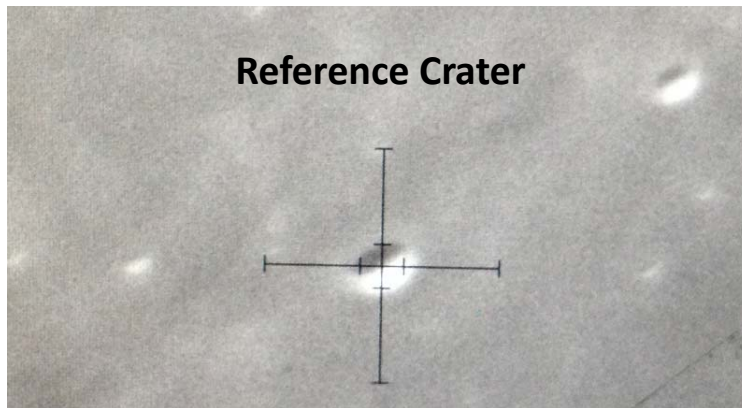


- 75 cm Telescope & 100 mJ Pulse Energy (2 pulses!)
- Return Rate $\sim 0.2\%$ @ 20 Hz
→ ~ 2.4 Echoes per Minute!!!
 - Elevation $> \sim 55$ deg
 - No blind tracking (also full moon difficult)
 - No reflector switching possible
 - LLR only in very good atmospheric conditions

Introduction

- LLR tracking procedure -

1. Crater referencing (many Thanks to OCA team!!!)
2. Reflector tracking & definition of a reference
3. Automatic telescope guiding wrt defined reference



-> first lunar echoes since many years in 2018 -> start of timeline

Introduction

- link budget -

- GOAL: achieve „real-time“ feedback (~1 echoe in 2 sec)
AND: support of weaker future targets (MoonLIGHT, etc.)

$$\frac{\#ECHOES}{SECONDS} \propto \frac{REFLECTOR \times \#SENT_{PHOTONS}}{DISTANCE^4} \times RepetitionRate \times Atmosphere$$

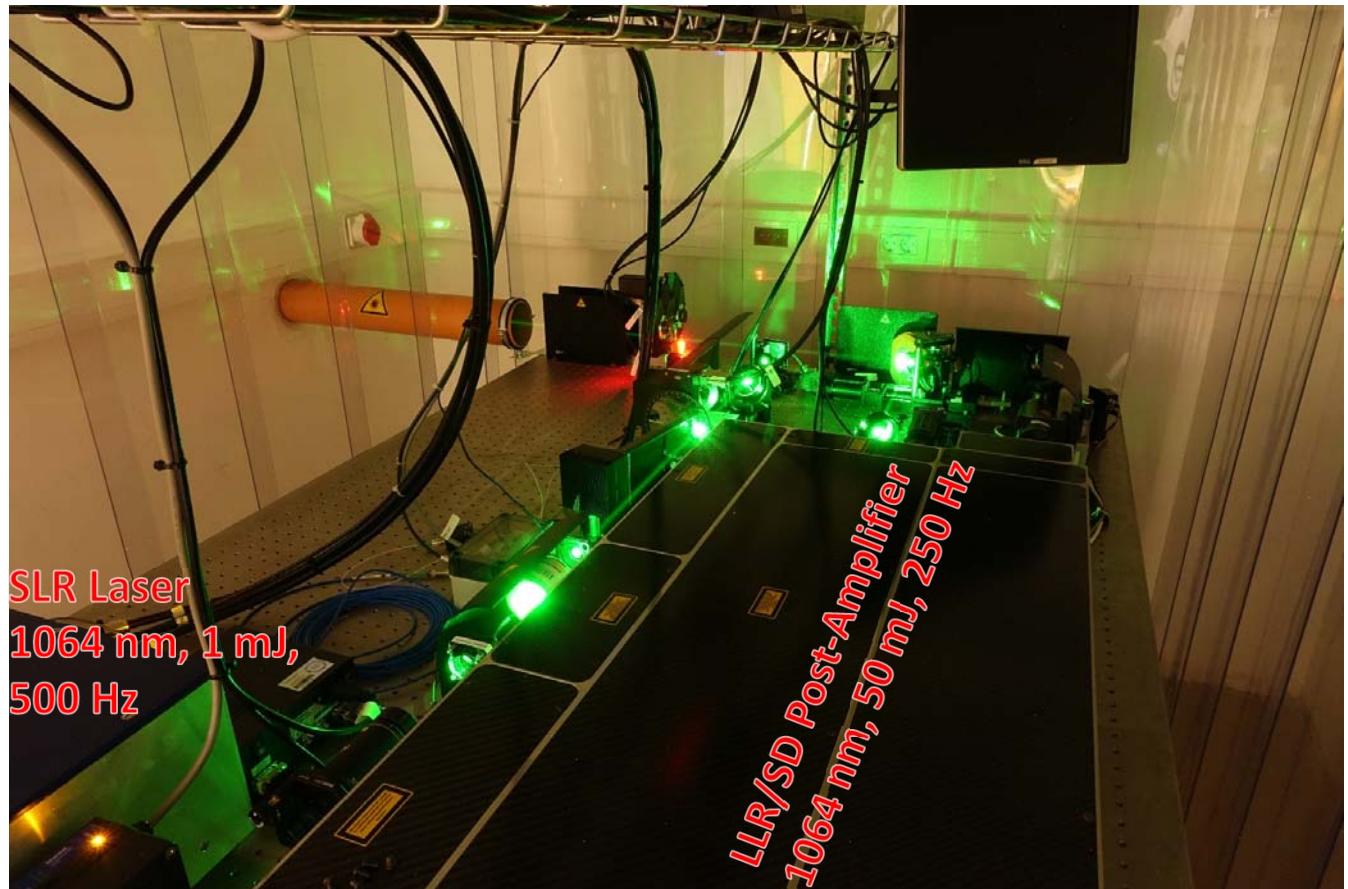
Diagram annotations:

- “given” points to $\frac{\#ECHOES}{SECONDS}$
- “Limited by max laser energy density” points to $\#SENT_{PHOTONS}$
- “given” points to $DISTANCE^4$
- “hHz T/R-switch @ monostatic WLRs setup for SLR since 2019
Straight forward: **Increase repetition rate also for LLR**” points to $RepetitionRate$
- “Maybe later” points to $Atmosphere$

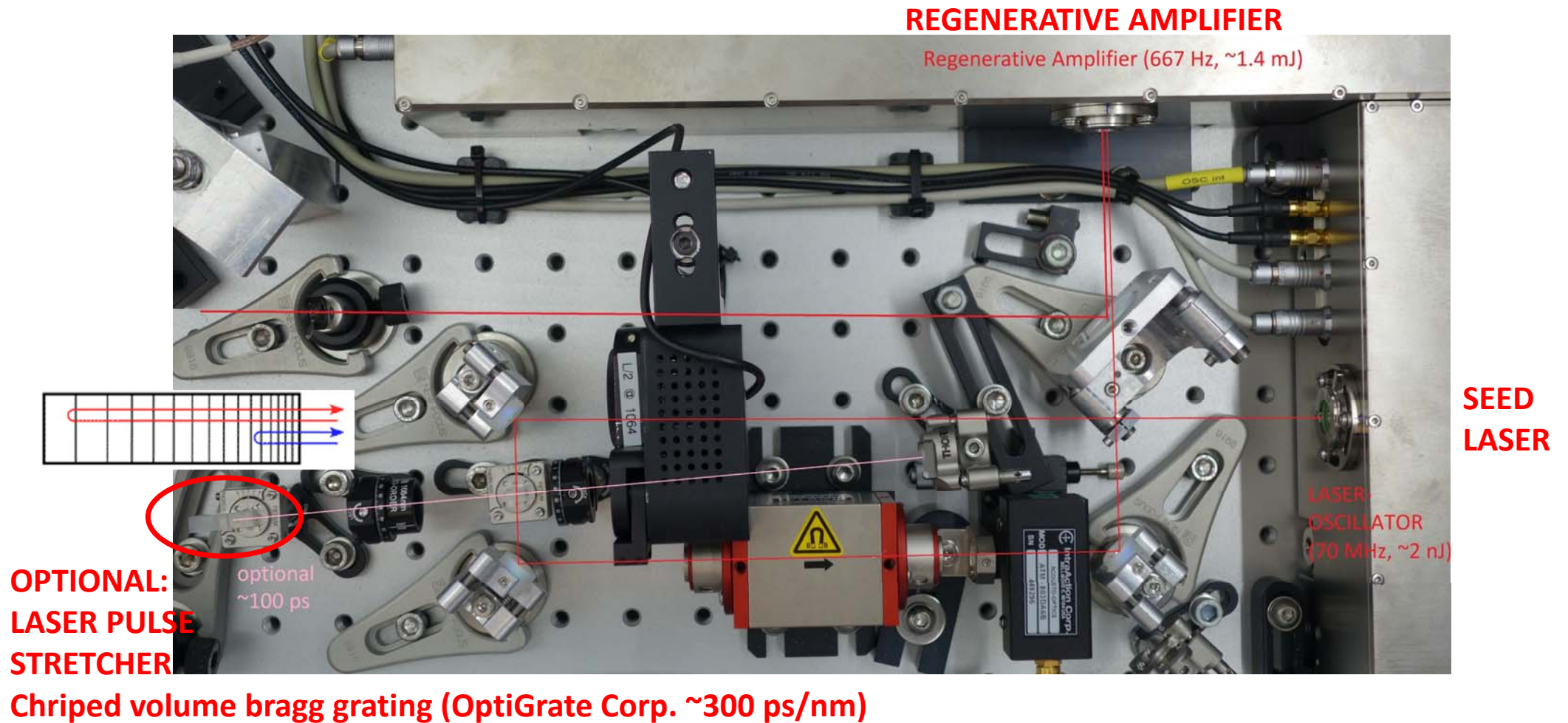
PART 1: Laser Upgrade

- phase 1 (diode pumped post amplifier) -

- Laser post amplifier upgrade to 250 Hz (InnoLas GmbH)
- Initial average power ~ 6 W (25 mJ)
- But:
 - Reduced single pulse energy (goal: factor 2, initial 8)
 - Use of polarisation dependent T/R switch necessary



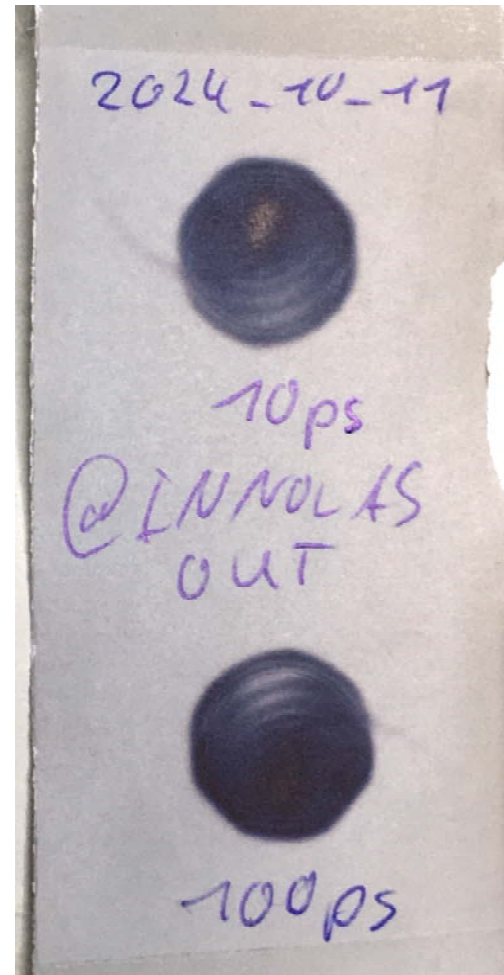
PART 1: Laser Upgrade - phase 2 (stretcher/compressor) -



PART 1: Laser Upgrade

- current status -

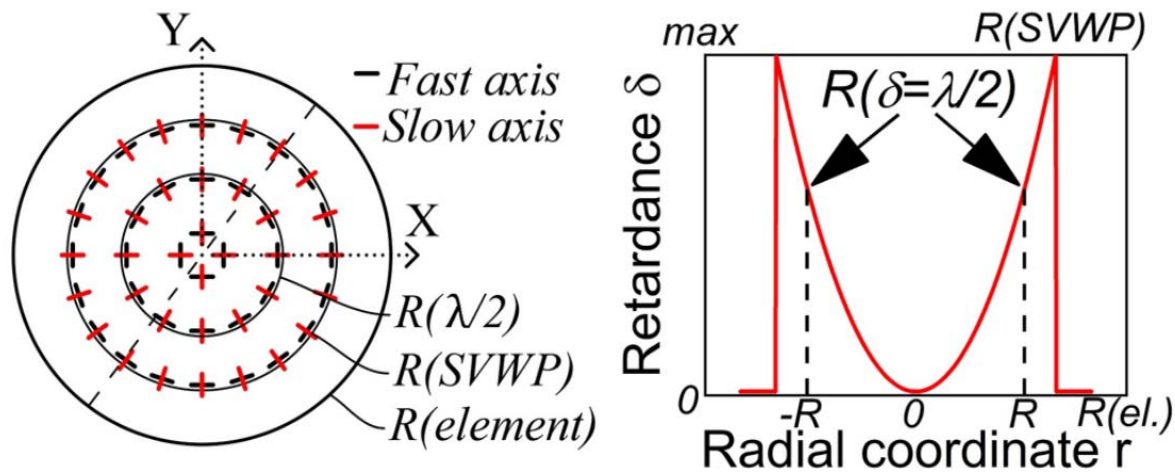
- Beam profile 100 ps smoother than 10 ps
- Due to implementations
→ realignment necessary
- Output Power: > 12 Watt



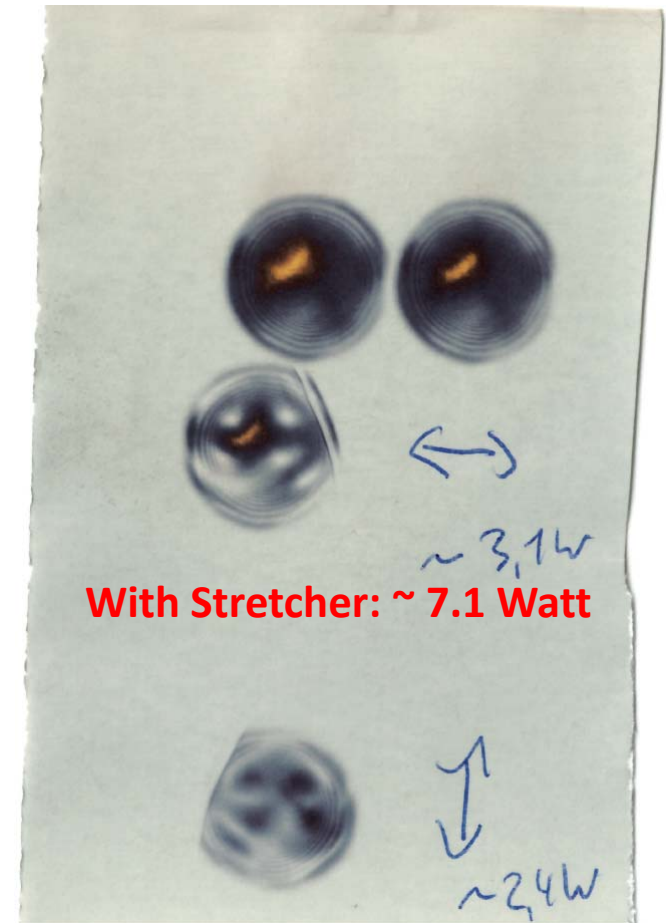
PART 1: Laser Upgrade

- depolarisation -

- Laser light depolarisation due to thermally induced birefringence in laser crystal



Laurynas V., et al.: "Depolarization compensation with a spatially variable wave plate in a 116 W, 441 fs, 1 MHz Yb:YAG double-pass laser amplifier", (2021)



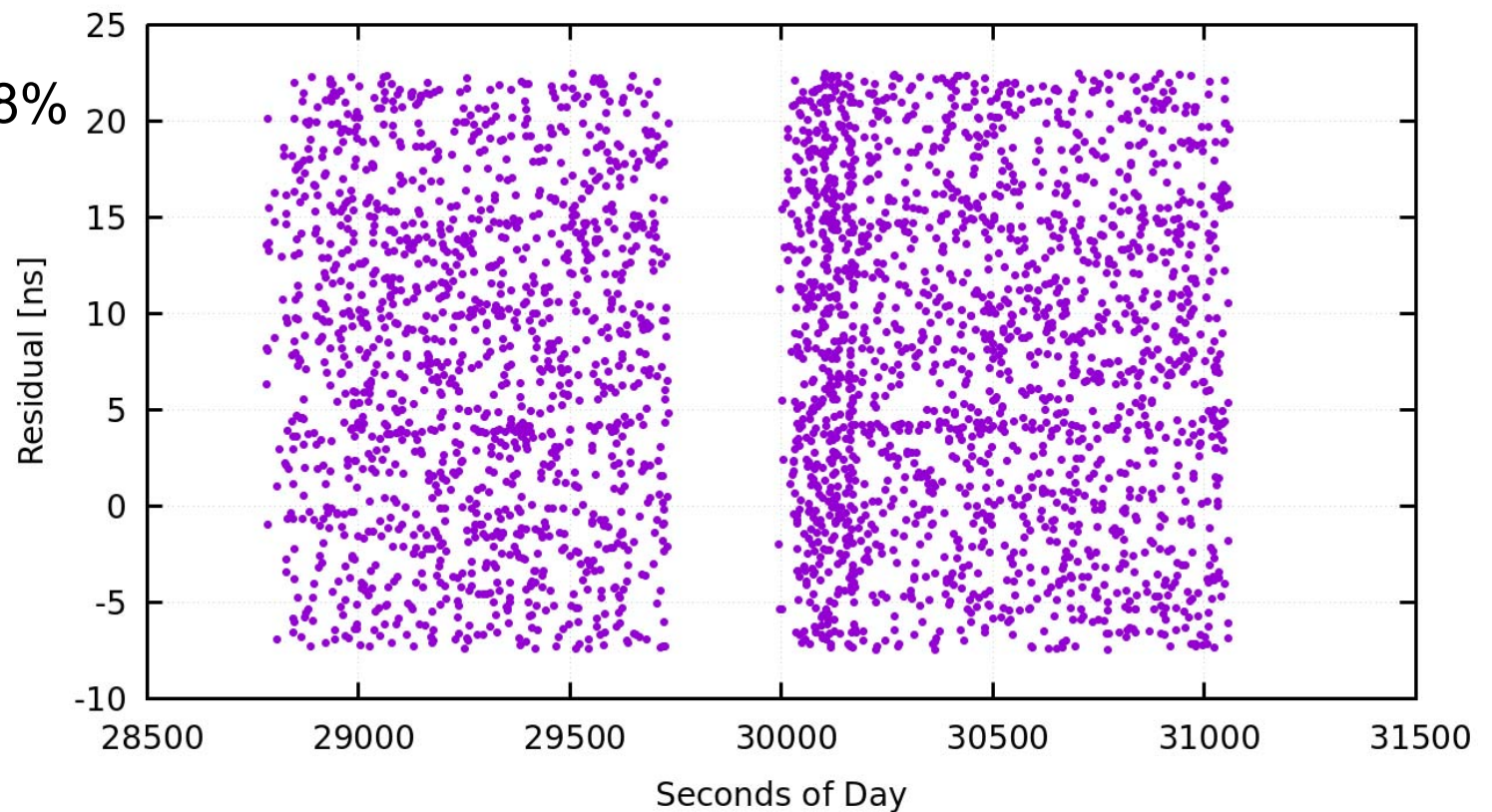
PART 1: Laser Upgrade

- first light after upgrade -

- Poor conditions during August 2024 → high humidity
- LUNA 17 ranging:
 - max. Echoe Rate $\sim 0.08\%$
(1 echoe / 5 sec)
 - S/N on the edge

Next Steps:

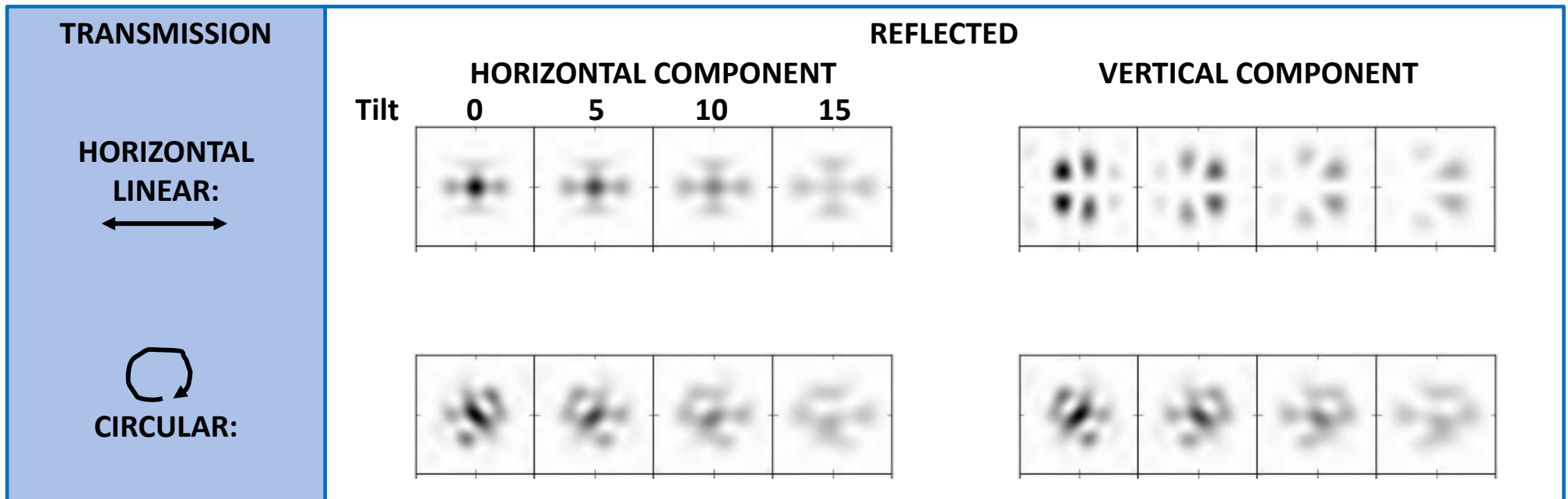
- Depolarisation compensation
- Beam profile optimisation



PART 2: T/R Upgrade

- FFDP of uncoated CCRs -

- Transmission of linear or circular polarised light possible..



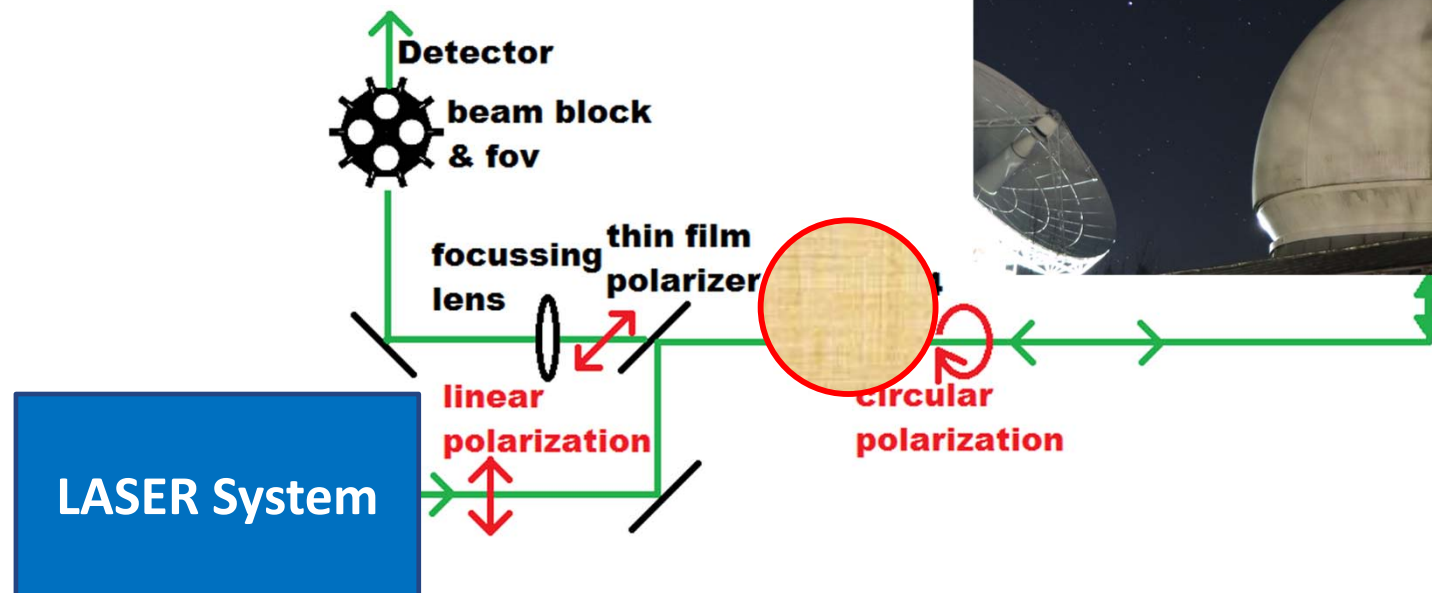
T. W. Murphy and S. D. Goodrow: "Polarization and far-field diffraction patterns of total internal reflection corner cubes", (2013)

- Detection of horizontal or vertical component possible (not both!)
- CIRCULAR: Energy of main lobe is split in both components (50% loss) → USE LINEAR!

PART 2: T/R Upgrade

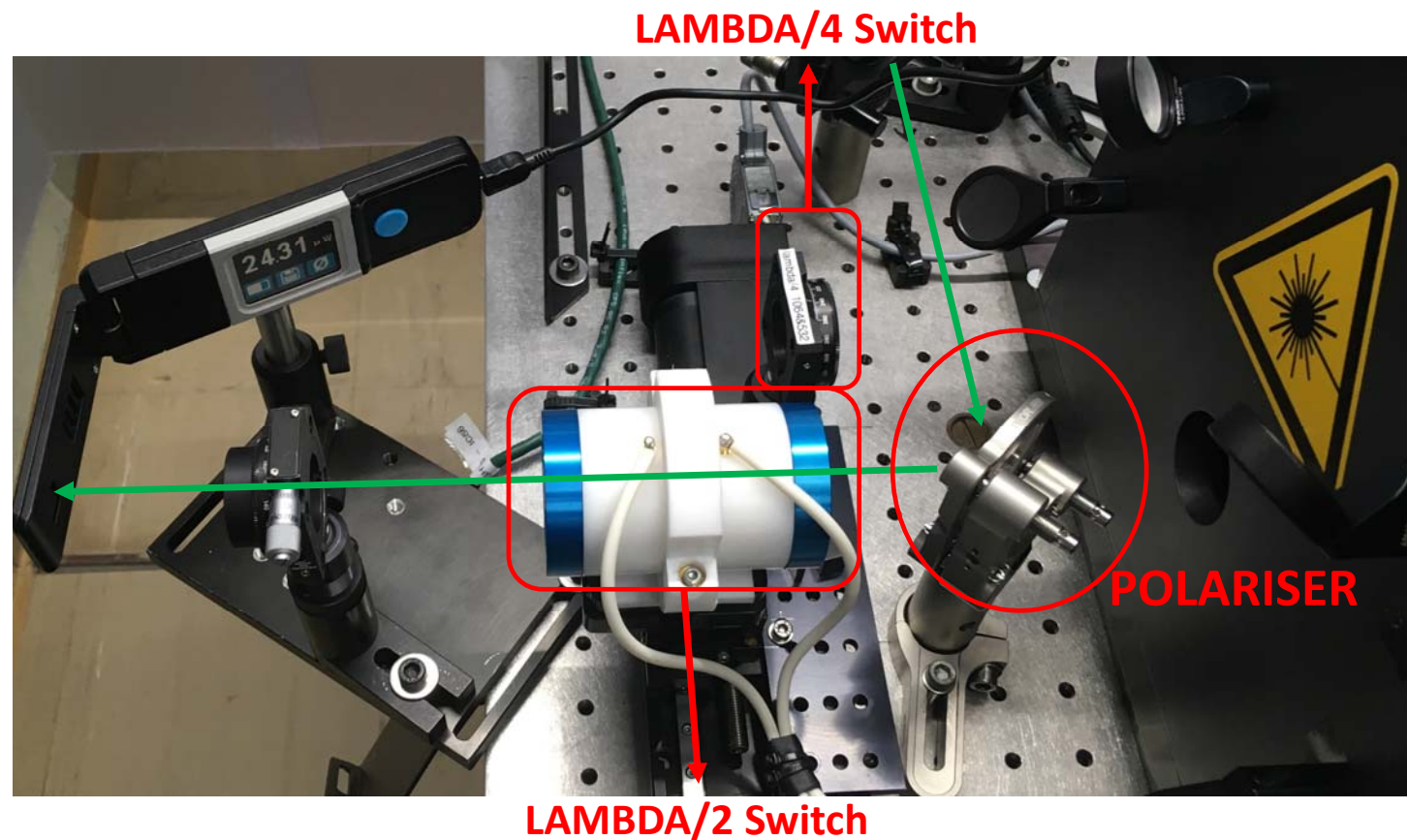
- Lambda/4 principle -

- Thin Film Polariser in combination with Lambda/4-plate (passive)
- Rotating beam block



PART 2: T/R Upgrade - implementation -

- 25 mm Aperture Pockels-Cell (G&H Photonics Centaur)
- Optional: L/4 or Pockels-Cell L/2 (circular or linear polarisation)

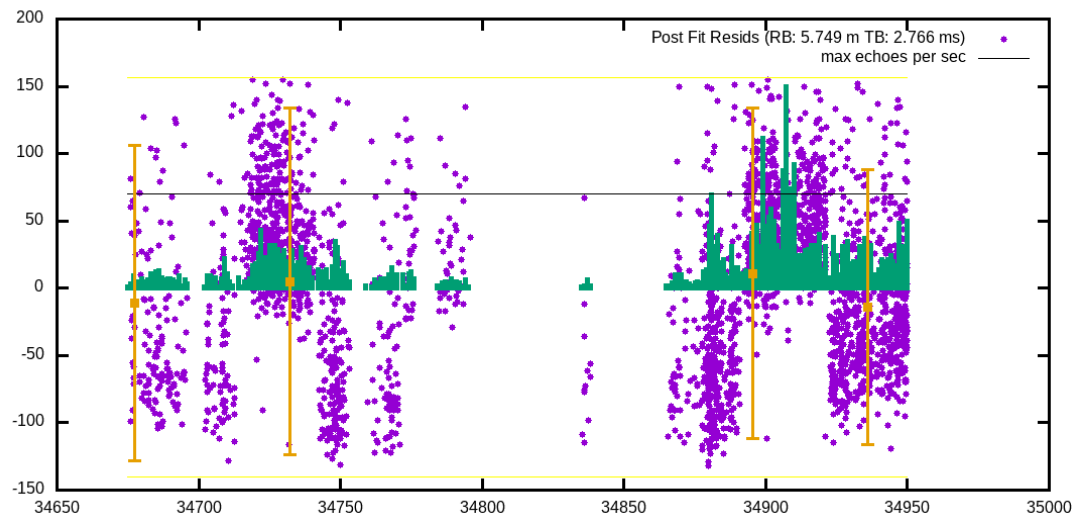


PART 2: T/R Upgrade - preliminary results -

- Return Rate variation when switching between circular & linear polarisation

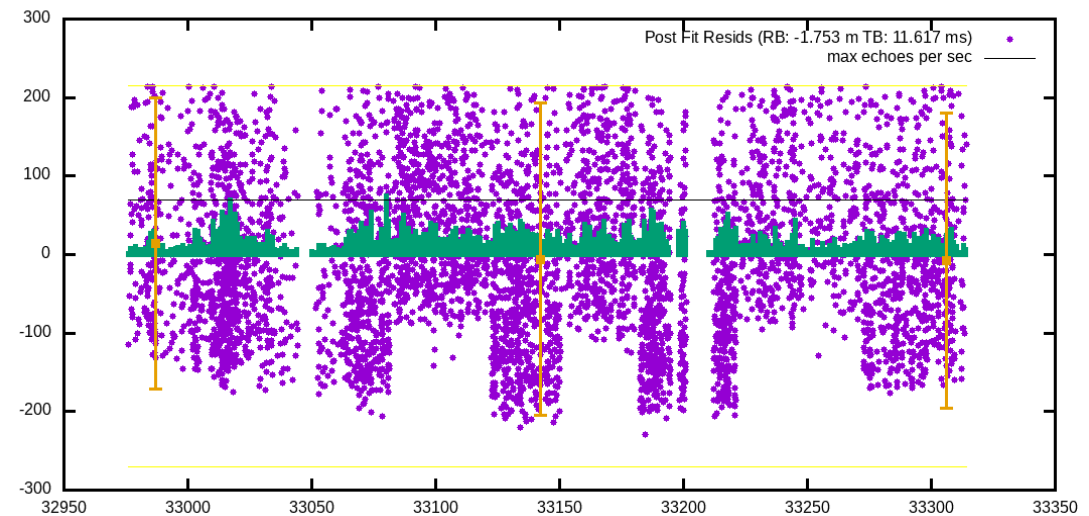
Uncoated CCR

lageos1 Total Echoes: 2856 RMS: 20.4 mm



Coated CCR

etalon1 Total Echoes: 5466 RMS: 33.1 mm



Conclusion

- PART 1:
 - Laser Upgrade Phase 2 finished: > 7 Watt usable laser power
 - In 08/2024 echoes from LUNA17 reflector (coated), after almost 1 year without data
 - Compensation of Depolarisation & Laser Beam profile optimisation pending
- PART 2:
 - T/R switch upgraded to use circular or linear polarised laser light for LLR & SLR
 - Functionality of PC half wave switch verified
 - LLR to uncoated Retroreflector arrays pending (APOLLO15, ...)
- Question: should we try to use linear polarisation for SLR (investigate LAGEOS response for circular and linear polarisation)???



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Thank you for your attention!

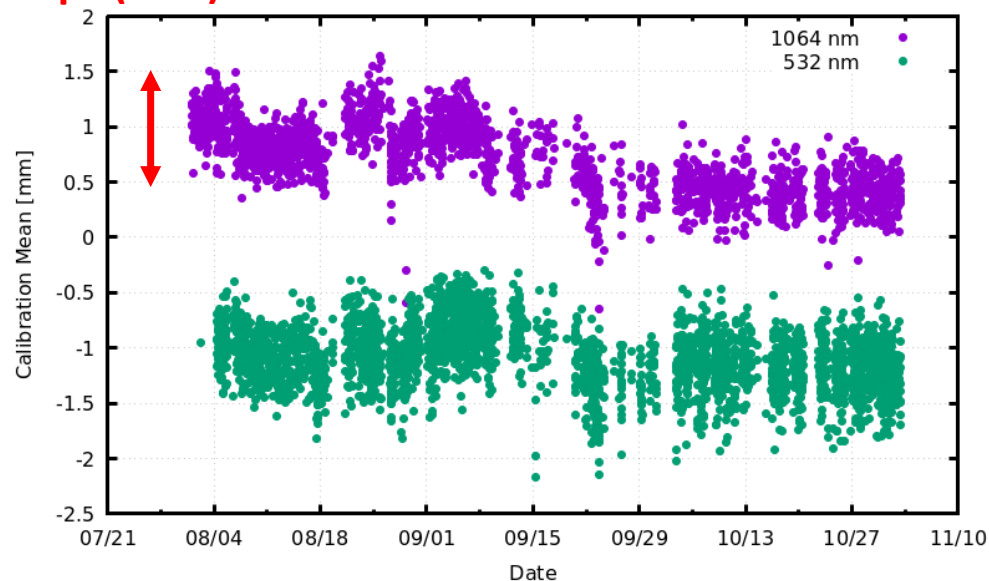
WLRS

- system calibration -

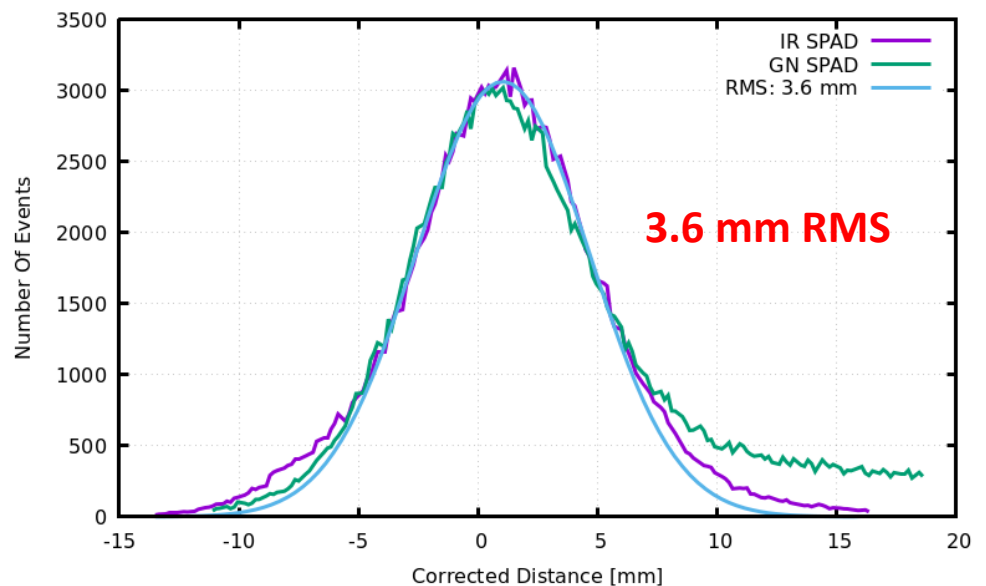
- Measurement to target with known distance to eliminate delay variations in electronics, cables, ... & determine system constant (absolute measurement)

1 mm (1-W)

6.7 ps (2-W)



3 months



Lunar Laser Ranging - link budget -

Received Number of Photoelectrons

$$\propto \text{Telescope Aperture} * \text{Pulse Energy} * \text{Detection Efficiency} * \text{Wavelength} \\ * \text{Transmit Gain} * \text{Reflector Cross Section}$$

Transmit Gain is function of pointing precision & atmospheric condition

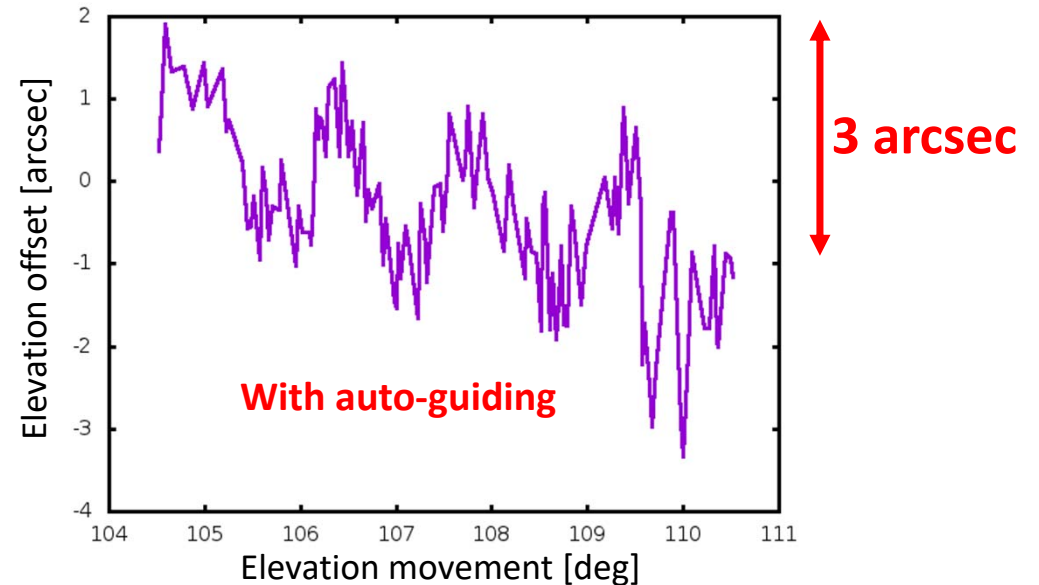
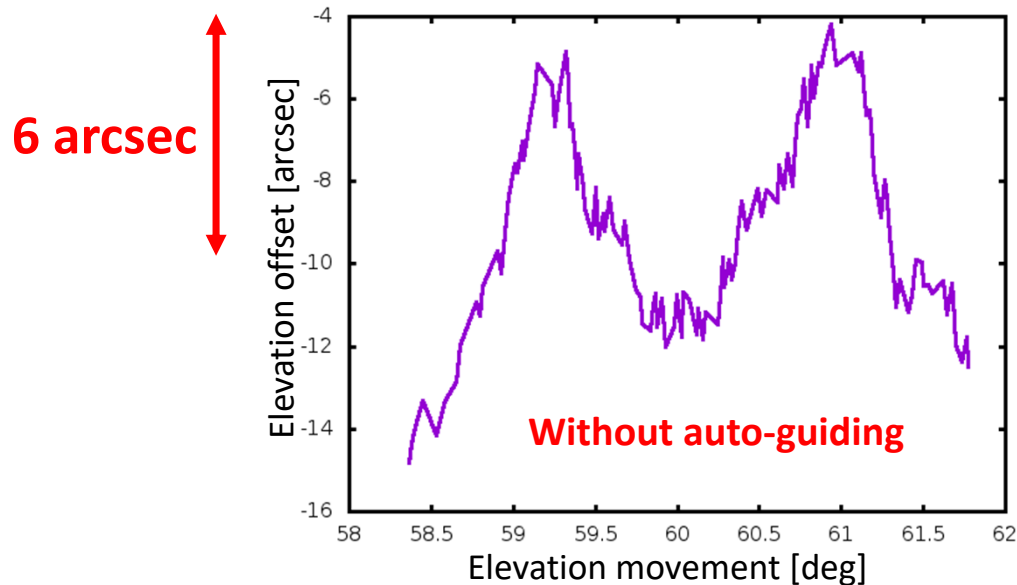
	APOLLO	Grasse MeO	Matera MLRO	WLRS
Telescope Aperture [m]	3.5	1.54	1.5	0.75
Laser Pulse Energy [J]	0.115	0.3 (0.2)	0.1	0.07 & 0.04
Detection Efficiency [%]	30	20 (20)	15	30
Wavelength [nm]	0.532	1.064 (0.532)	0.532	1.064
Elevation [m]	2788	1323	540	665

- WLRS link budget more than one order of magnitude below best performing LLR systems.
- Considering just number of photons, Ranging @ 1064 nm provides ~ factor 4 gain in signal strength.

WLRS

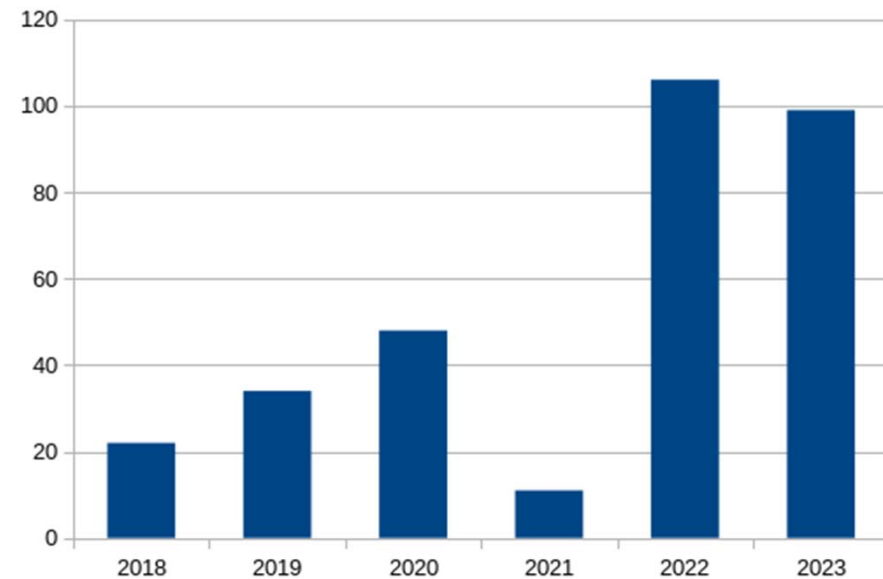
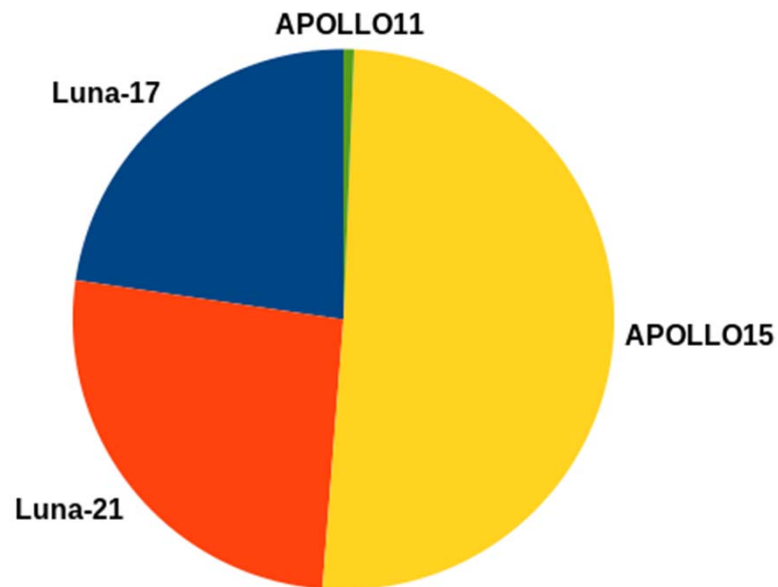
- telescope tracking issue -

- Tracking error discovered (caused by worm gear)
- Workaround needed
- Camera assisted automatic guiding
- Tracking performance verified by star tracking → Residual RMS error < 1 arcsec



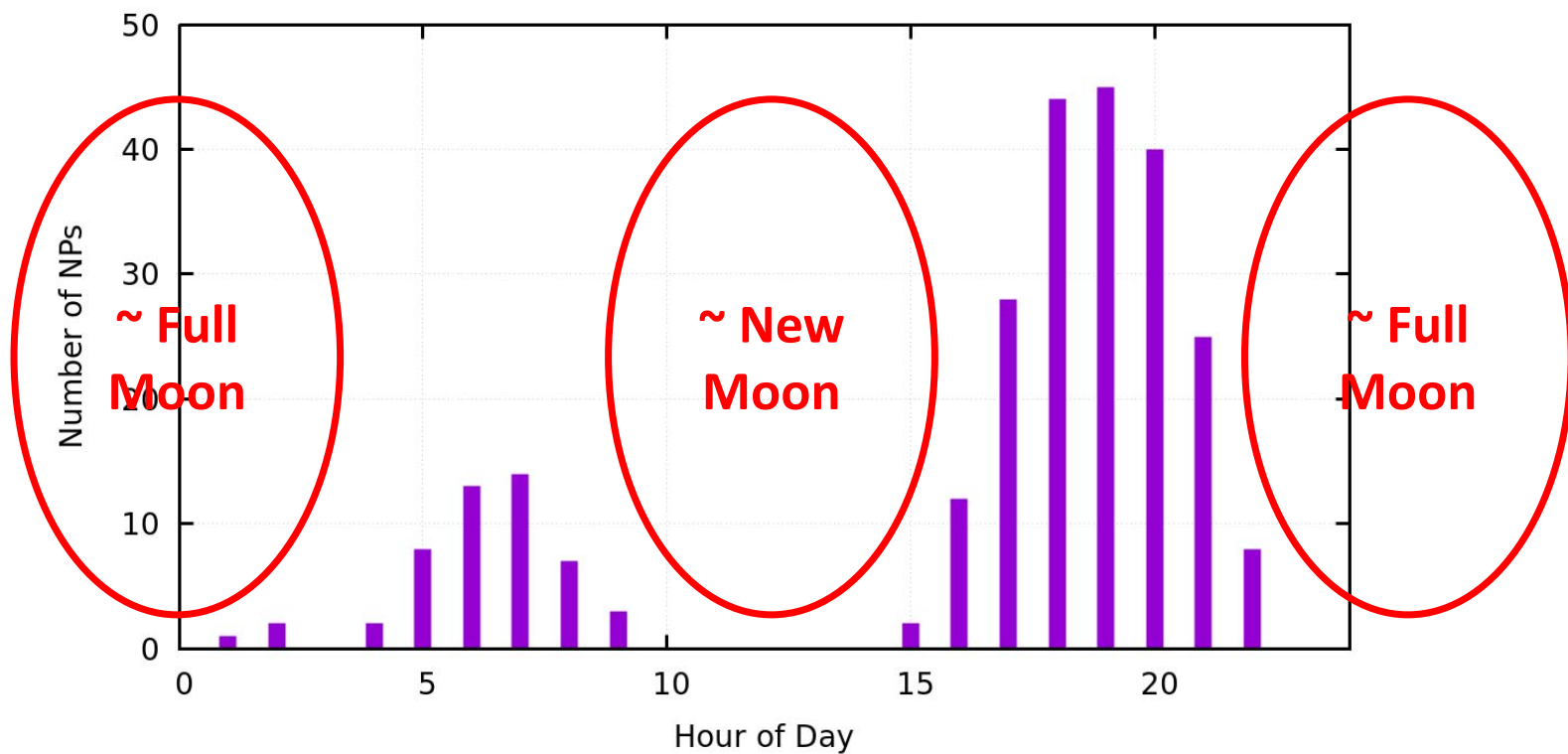
Lunar Laser Ranging - measurements so far ... -

- Target distribution depending mostly on visibility of tracking reference point
- Steady rise of number of „Normal-Points“ since start in 2018



Lunar Laser Ranging - hour of day -

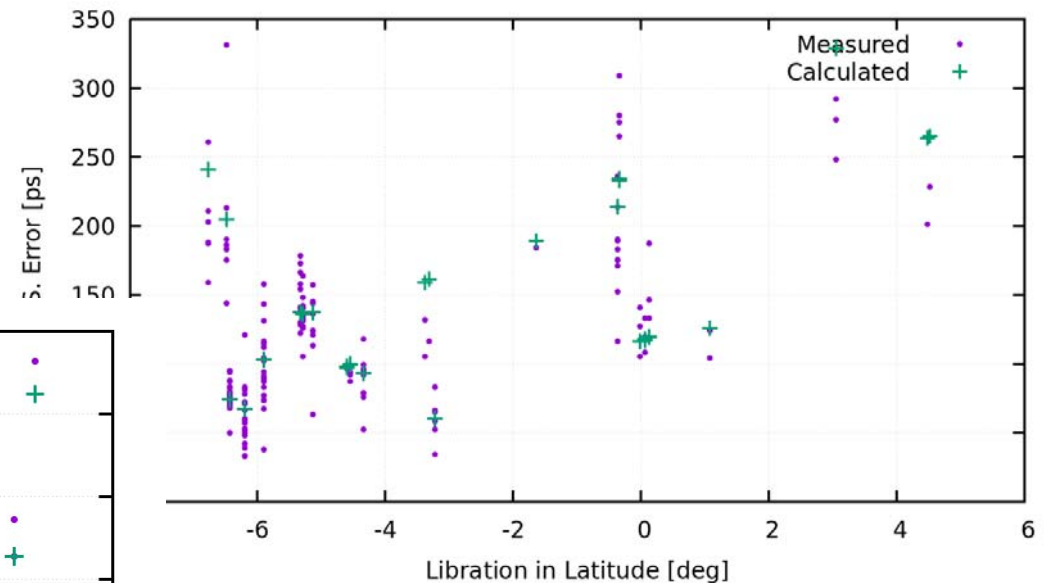
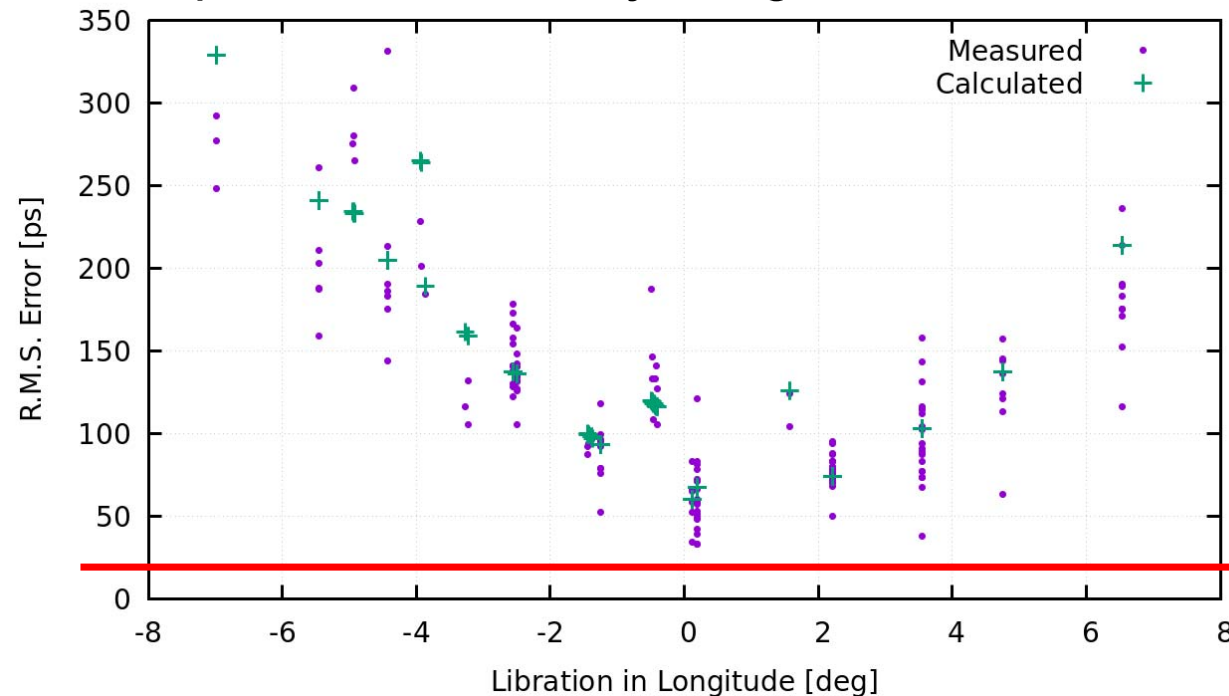
- Daytime ranging uncritical
- Due to Elevation > 55 deg \rightarrow hour of day represents \sim lunar phase



Lunar Laser Ranging

- APOLLO 15 LRA Target Signature -

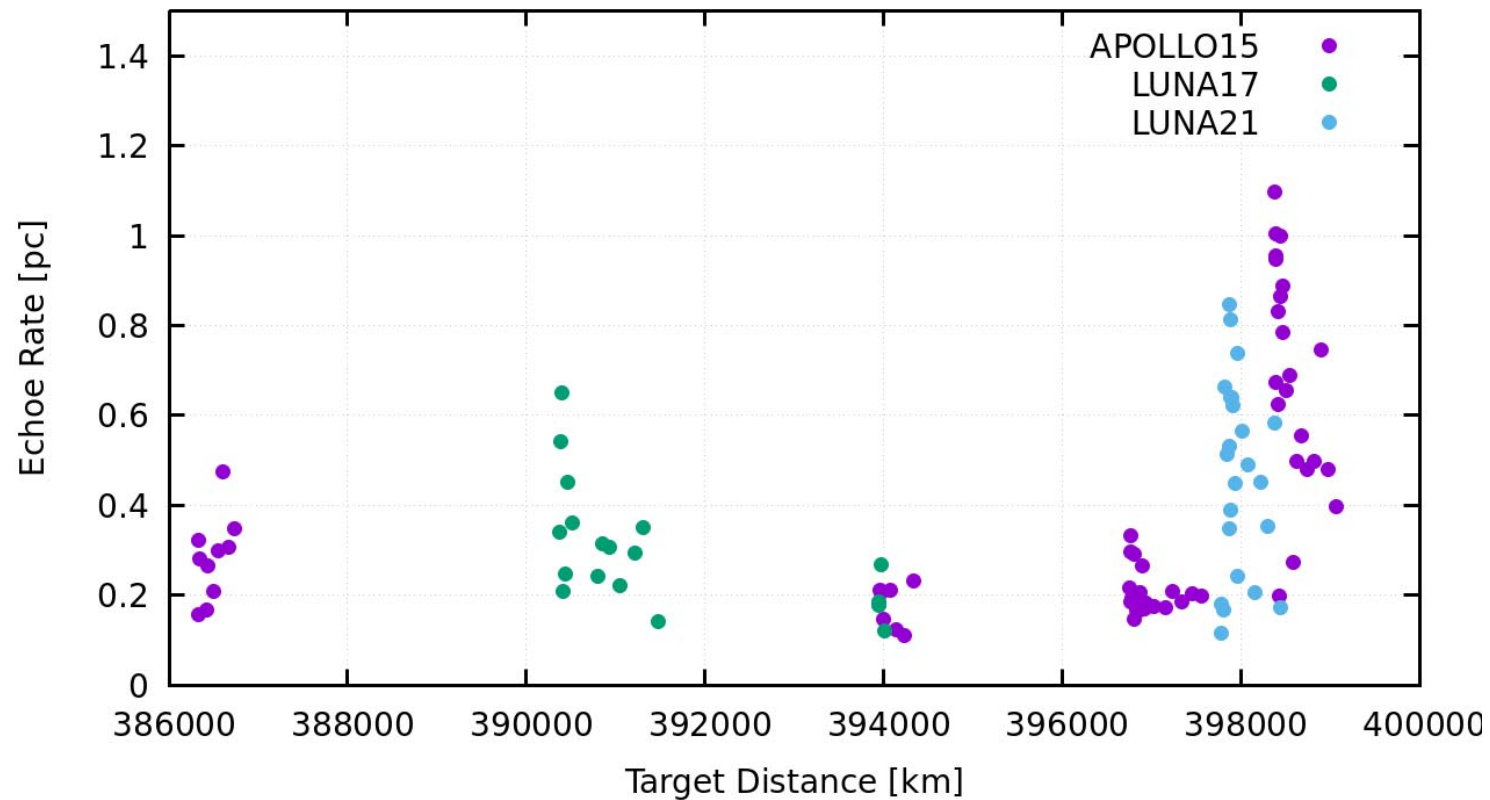
- Simple rectangular reflector model, tilted with libration
- Found reflector offset pointing of -1.1 lon & 4.3 lat deg wrt WLRS position, when adjusting the data



- Method for quality control (good indicator for systematic error)
→ Time correlated single photon counting

WLRS intrinsic timing precision

Lunar Laser Ranging - echoe rates in 2023 -



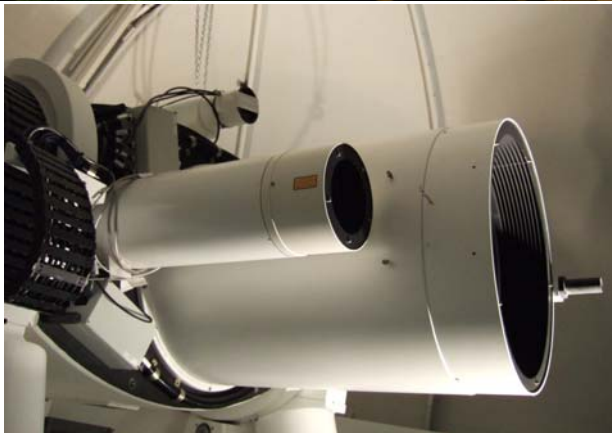
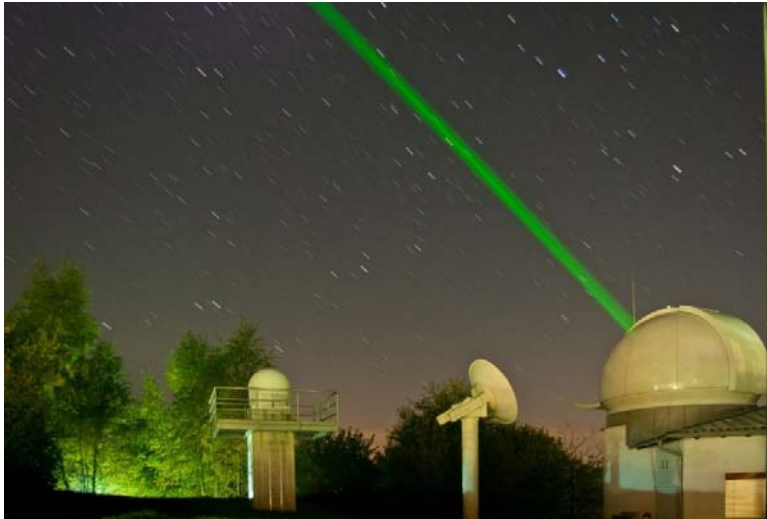
Further Outlook & Conclusion

- Fortunately had some money during the last years:
 - Guide star laser
 - Deformable mirror
- GOALS: blind tracking capability & reduce minimum possible elevation

Conclusion:

- LLR timeline started in 2018
- Can not compete with LLR partner stations in terms of amount of data
- Focus on best possible precision and accuracy in combination with connection to reference frames & clocks (SI second)
- With ongoing/upcoming upgrades: Support new Missions with improved CCR!

Laser Ranging Systems



Wettzell Laser Ranging System (WLRS, 1990)

- 75 cm monostatic telescope
 - Identical beam path for transmit/receive
 - Pointing accuracy of optical axes 0,5 "
- Nd:YAG pulse laser
 - 532 nm (green) or 1064 nm (NIR)
 - Pulse width 10 ps (3 mm)
 - 667 pulses per second (20 for LLR)
- Observations
 - Satellites (all heights)
 - **Lunar Laser Ranging**, Space Debris Ranging
 - Scientific projects, e. g. Time Transfer

Satellite Observing System Wettzell (SOS-W, 2014)

- 16 cm / 50 cm bistatic telescope
- Ti:SAP pulse laser
 - 425 nm (blue) or 850 nm (NIR)
 - 1000 pulses per second (1 kHz)
- Observations
 - Satellites (all heights)

Next Steps

- Depolarisation
- Re-Alignment & improved air conditioning
- Optimisation beam profile

Introduction

- in the past -

- ??? : Long accumulation times necessary to identify lunar echoes
- RR $\sim 0.2\%$ @ 20 Hz $\rightarrow \sim 2.4$ Echoes per Minute!!!
- Pointing optimisation during ranging NOT possible
- Instead: Optimise pointing wrt crater position & auto-guiding